# Hybrid III ATD – 50<sup>th</sup> Male RibEye<sup>™</sup> A Better Way to Measure Thorax Displacement



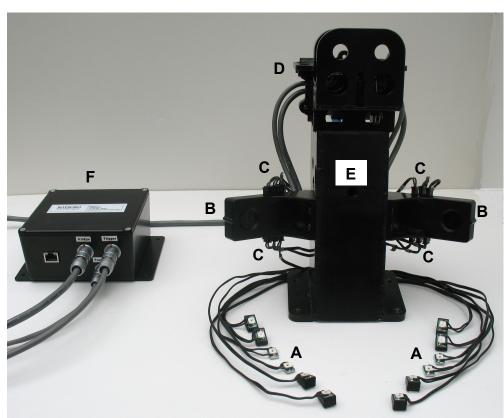
## **Measurement Capabilities**

- Accuracy +/- 0.2 mm typical +/- 1 mm max. error
- Range
  - X axis: up to 85 mm chest compression Y axis: +/- 90 mm from center of spine Z axis from top rib to bottom rib
- Acquisition time @ 10 kHz sample rate 30,000 ms (30 seconds) in RAM 2 seconds in flash memory (500 ms pre-trigger/1500 ms post-trigger)
- Temperature range Operating, -18°-38°C (0°-100°F) Max. accuracy, 18°-29°C (65°-85°F)

## **RibEye Advantages**

- Multiple point measurement: 12 points @ 10 kHz sample rate, captures linear and oblique loads
- Multiple-axis: measures X and Y positions for each LED
- Non-contact: no mechanical linkages between spine and ribs
- Shows seat-belt loading effects on all ribs
- Simple installation of LEDs
- Interfaces with existing data acquisition systems: open protocol for RibEye operation by DAS software
- Meets ISO 6487-2000 and SAE J211 specifications





#### **RibEye Components**

- A 12 LEDs mounted on ribs at measurement points
- **B** Two optical sensor heads to derive LED positions
- C LED connector blocks built into sensor heads
- **D** RibEye controller mounted in back of spine
- E New spine modified for mounting the RibEye
- **F** Trunk box (power, trigger, and communications connectors), located externally

## **Other information**

- PC-based control software exports data in Diadem, ISO, or CSV formats (PC not included)
- Power requirement: 12-36 Volts DC
   8.3 W (data acquisition)
   5.3 W (idle)
   12.3 W (max.)
- U.S. Patent Number 7508530
- For more data, please see our website literature, including papers from the 2011 ESV Conference about third-party testing using the RibEye

www.boxborosystems.com

		RibEye St	atus		
		Connecte	RibEye T	ype: 50th Male	
onneo	t to RibEy	e via: IP	Address	Serial Num	ber: 00075
and the second second	hernet		68.0.152 DISCONNEC	Calibration D	ate: 25 January 2010
		Find	RibEyes	Firmware Versi	on: 50 \$0005
				RibEy	e Installed in ATD:
					HIII 50TH
					Trigger Setting
		ISO Test Object	1 - Vehicle 1		Rising Edge
		· · · · · · · · · · · · · · · · · · ·			
		ISO Position	1 - Front Left	Show Cur	rent XY's
LED	RIB	POSITION	ISO CODE S	X (mm)	Y (mm)
1	1	LEFT	1 1 RIBS 01 LE H3 DS X/Y	0.0	0.0
2	2	LEFT	1 1 RIBS 02 LE H3 DS X/Y	0.0	0.0
3	3	LEFT	1 1 RIBS 03 LE H3 DS X/Y	0.0	0.0
4	4	LEFT	1 1 RIBS 04 LE H3 DS X/Y	0.0	0.0
5	5	LEFT	1 1 RIBS 05 LE H3 DS X/Y	0.0	0.0
6	6	LEFT RIGHT	1 1 RIBS 06 LE H3 DS X/Y 1 1 RIBS 01 RT H3 DS X/Y	0.0	0.0
Γ	ARM		Data Buffer Operation		RibEye (ms)
			Circular 🛥 Linear	Start Time	Stop Time
ERA	SE MEMORY	Da	ta to collect after Trigger (ms)	-500	1500
			2000	Data To	Download (ms)
		7		Start Time	Stop Time
DOV	NLOAD DATA	d.		-10	400
				1	100
10 Davb	oro Systems LLC				

# Hybrid III ATD – 5<sup>th</sup> Female RibEye<sup>™</sup> A Better Way to Measure Thorax Displacement

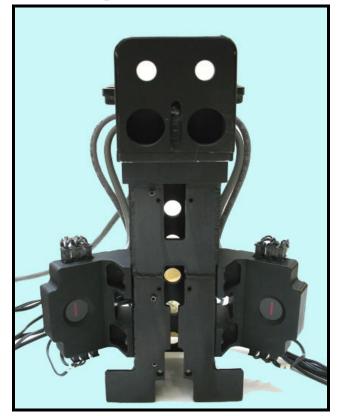


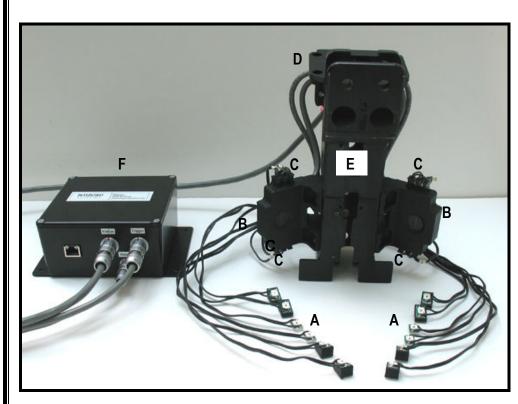
## **Measurement Capabilities**

- Accuracy
   +/- 0.2 mm typical
   +/- 1 mm max. error
- Range
  - X axis: up to 60 mm chest compression Y axis: +/-75 mm from center of spine Z axis from top rib to bottom rib
- Acquisition time @ 10 kHz sample rate 30,000 ms (30 seconds) in RAM 2 seconds in flash memory (500 ms pre-trigger/1500 ms post-trigger)
- Temperature range Operating, -18°-38°C (0°-100°F) Max. accuracy, 18°-29°C (65°-85°F)

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   8.3 W (data acquisition)
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   12.3 W (max.)
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- For more data, please see our website literature, including papers from the 2011 ESV Conference about third-party testing using the RibEye

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		RibEye St	atus		
		Connecte	d - Idle	RibEye Typ	e: 50th Male
onnec	t to RibEye	evia: IP	Address	Serial Numbe	r: 00075
Eth	ernet	▼ 192.1	68.0.152 DISCONNEC	T Calibration Date	e: 25 January 2010
		Find	RibEyes	Firmware Version	: 50 \$0005
				RibEye li	nstalled in ATD:
					HIII 50TH
				Tr	igger Setting
		ISO Test Object	1 - Vehicle 1		ing Edge
		ISO Position	1 - Front Left 💌	Show Curren	nt XY's
LED	RIB	POSITION	ISO CODES	X (mm)	Y (mm)
1	1	LEFT	1 1 RIBS 01 LE H3 DS X/Y	0.0	0.0
2	2	LEFT	1 1 RIBS 02 LE H3 DS X/Y	0.0	0.0
3	3	LEFT	1 1 RIBS 03 LE H3 DS X/Y	0.0	0.0
4	4	LEFT	1 1 RIBS 04 LE H3 DS X/Y	0.0	0.0
5	5	LEFT	1 1 RIBS 05 LE H3 DS X/Y	0.0	0.0
6 7	6	LEFT RIGHT	1 1 RIBS 06 LE H3 DS X/Y 1 1 RIBS 01 RI H3 DS X/Y	0.0	0.0
	ARM		Data Buffer Operation Circular 🛶 Linear	Data in Ri Start Time -500	bEye (ms) Stop Time 1500
ERA	E MEMORY	Da	ta to collect after Trigger (ms)		1000
			2000	Data To Do	wnload (ms)
DOW	NLOAD DATA	1		Start Time	Stop Time
0000	ILUAD DATA	9		-10	400

# WorldSID ATD – 50<sup>th</sup> Male RibEye<sup>™</sup> A Better Way to Measure Thorax Displacement



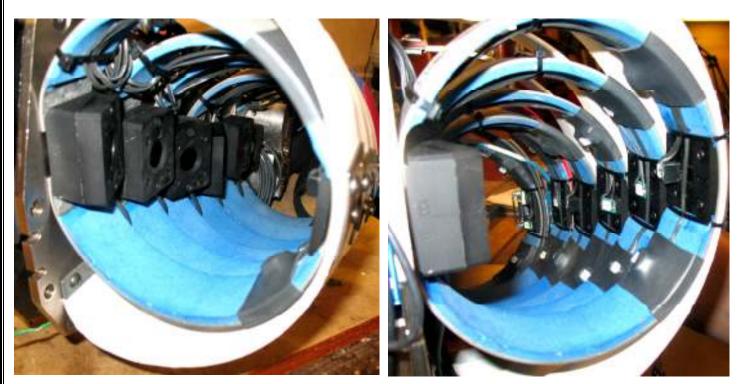
## **Measurement Capabilities**

- Accuracy
   For Y and Z data:
   <u>+</u> 0.2 mm typical
   <u>+</u> 1 mm max. error
   For X data, max. error <1.5 mm</p>
- Range
  - X axis:  $\pm$  130 mm fore/aft Y axis: 85 mm chest compression Z axis: 80 mm up, 50 mm down
- Acquisition time @ 10 kHz sample rate 25,000 ms (25 seconds) in RAM 1.7 seconds in flash memory
- Temperature range Operating, -18°-38°C (0°-100°F) Max. accuracy, 18°-24°C (65°-75°F)

## **RibEye Advantages**

- Multiple point measurement: 18 points @ 10 kHz sample rate, captures linear and oblique loads
- Six-LED version also available
- Multiple-axis: measures X, Y and Z positions for each LED
- Non-contact: no mechanical linkages between spine and ribs
- Mounts to existing holes in spine and ribs no modifications to dummy
- Interfaces with existing data acquisition systems: open protocol for RibEye operation by DAS software
- Meets ISO 6487-2000 and SAE J211 specifications





**RibEye Sensors** 

**RibEye LEDs** 

#### **More information**

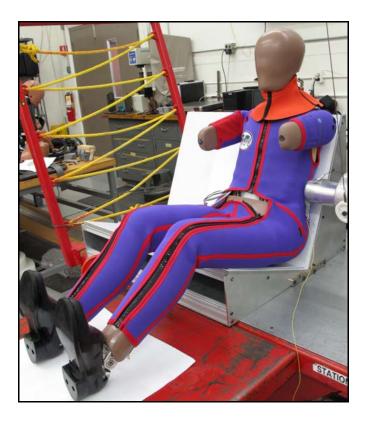
- PC-based control software exports data in Diadem, ISO, or CSV formats
- Power requirement: 12-36 Volts DC
   8 W (idle)
   12 W (data acquisition)
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- U.S. Patent Number 7508530
- For more data, please see our website literature, including user's manuals and technical conference papers about third-party testing using the RibEye

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RibEye Status									and the second						
Connected - Idle								RibEye Type: WorldSID M							
Connect to RibEye via: IP Address								Serial N	umber:	112					
Et	vernet	• 192	.168	.0.	0.237 DISCONNECT					NECT	Calibration Date:		29 Nov 2012		
		Fir	id R	bЕ	yes					F	innware V	ersion:	W\$50BS	001	
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												Trigger 5	etting		
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		ISO Positi	on:	F	1.Fn	net l	eft	*			11	and the second			
				-		one c	010				Show Cu	irrent XYZ	1		
LED	RIB	POSITION				150	000	)E\$			X (mm)	Y (mm)	Z (mm)	A	
1	1	REAR			SERI		RE	₩S.	DS	XYZ	-58.8	-77.1	-52.3		
2	1	MIDDLE			SERI			₩5			-28.9	-92.3	-54.0	-	
3	1	FRONT	1		SHRI						23.4	-77.8	-68.0	4	
4	2	REAR		_	TERI			¥5			-45.2	-92.7	-2.0	-	
5	2	FRONT		-	TERI			VS VS	land at		-1.5	-107.9	-1.0		
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			0	300	ular a		Line	ar			Start Tir	ne Sta	up Time		
FRAS	E MEMORY	18 8	and and		ollect						-200		1500		
Chest	L ML MONT	a	1010	10 C		000	ing	ger (r	392		Data T	o Downlo	ad (ms)		
DOWN	LOAD DAT										Start Tir	ne Sta	p Time		
Lociali	COMP DATE	24. I									10	1.5	400		

## WorldSID ATD – 5<sup>th</sup> Female RibEye<sup>™</sup> A Better Way to Measure Thorax Displacement

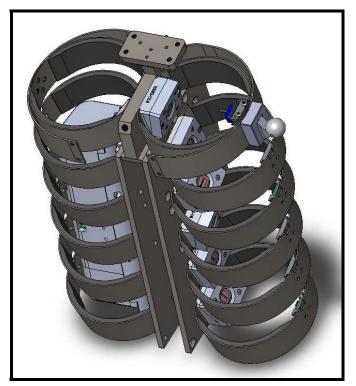


## **Measurement Capabilities**

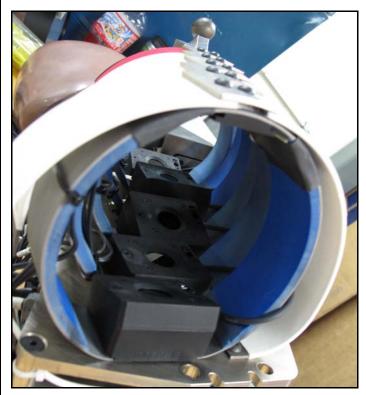
- Accuracy
   For Y and Z data:
   <u>+</u> 0.2 mm typical
   <u>+</u> 1 mm max. error
   For X data, max. error < 1.5 mm</p>
- Maximum range X axis: <u>+</u> 120 mm fore/aft Y axis: 67 mm chest compression Z axis: 80 mm up, 65 mm down
- Acquisition time @ 10 kHz sample rate 25,000 ms (25 seconds) in RAM 1.7 seconds in flash memory
- Temperature range Operating, -18°-38°C (0°-100°F) Max. accuracy, 18°-24°C (65°-75°F)

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WorldSID 5th Female RibEye Thorax



**RibEye Sensors** 



**RibEye LEDs** 

#### **More information**

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- Power requirement: 12-36 Volts DC
   8 W (idle)
   12 W (data acquisition)
   20 W (max.)
- U.S. Patent Number 7508530
- For more data, please see our website literature, including user's manuals and technical conference papers about third-party testing using the RibEye

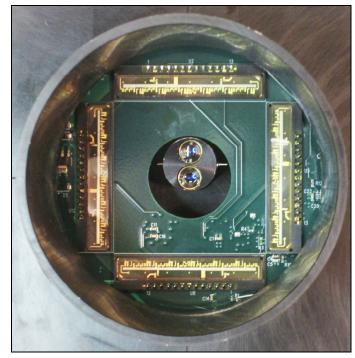
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Connect/Setup Plot Live Display Export									
RibEye Status									
Connected - Idle RibEye Type: WorldSID Male									
Connect to RibEye via: IP Address Serial Number: 112									
Ethernet T 192.168.0.237 DISCONNECT Calibration Date: 29 Nov 2012									
Find RibEyes         Firmware Version:         WS50BS001									
RibEye Installed in ATD:									
RibEye Pointed Toward Dummy Left Side 💌 wsid 50th #2									
Trigger Setting									
ISO Test Object 1 - Vehicle 1 💌 Rising Edge 💌									
ISO Position 1 - Front Left Show Current XYZ's									
LED RIB POSITION ISO CODES X (mm) Y (mm) Z (mm)									
1 1 REAR 1 1 SHRI 00 RE WS DS XYZ -58.8 -77.1 -52.3									
2 1 MIDDLE 1 1 SHRI 00 MI WS DS XYZ -28.9 -92.3 -54.0									
3 1 FRONT 1 1 SHRI 00 FR VS DS XYZ 23.4 -77.8 -60.0									
4 2 REAR 1 1 THRI 01 RE VS DS XYZ -45.2 -92.7 -2.0									
5 2 MIDDLE 1 1 THRI 01 MI WS DS XYZ -1.5 -107.9 -1.0									
6 2 FRONT 1 1 THRI 01 FR WS DS XYZ 45.2 -94.2 -2.8 x									
ARM Data Buffer Operation Data in RibEye (ms) Circular Linear Start Time Stop Time 200 1500 Data to collect after Trigger (ms) 2000 Data To Download (ms) Start Time Stop Time									
© 2012, Boxboro Systems LLC									

#### s y s t e m s Deflection and Twist Measurement System (DTMS™)

A Better Way to Measure Dynamic Motion in Large Structures



BOXBORO

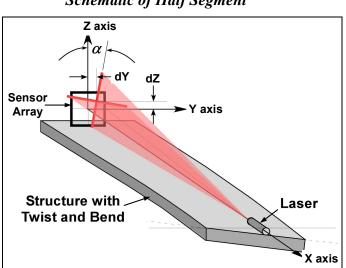
Sensor Array and Cross-Hair Laser

## **Description and Capabilities**

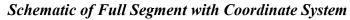
- Scalable laser tool available in half or full segments or string of multiple segments
- Applications include bridges, buildings, boat hulls, trains, crane booms, vehicle frames, and airplane wings
- Accuracy certified by independent U.S. lab with NIST/NPL traceability
- Deflection and twist reported in real time
  - Deflection accuracy: 0.2 mm
  - Twist accuracy: 0.1 degree
  - Frequency response: up to 100 Hz
- Y, Z measurement range per segment
  - 0 to 47 mm (+/- 23.5 mm)
- Maximum twist
  - X axis: 35 degrees per segment
  - Y, Z depend on number of segments

#### **DTMS Advantages**

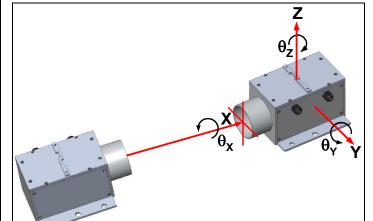
- Measures five degrees of freedom at multiple points selected by the user
- Records and displays dynamic mode shapes while the structure is moving
- Reports data relative to one end of the structure, not a fixed ground reference
- Results are not affected by the structure's motion or acceleration
- Accommodates unusual structural shapes and can be mounted inside hollow spaces
- Software included to provide configuration, data logging, and three ways to plot
- Simple communication via Modbus RTU protocol over RS485 network



#### Schematic of Half Segment

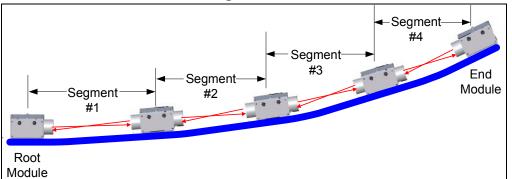


DTMS Module Enclosure in Multi-Segment System

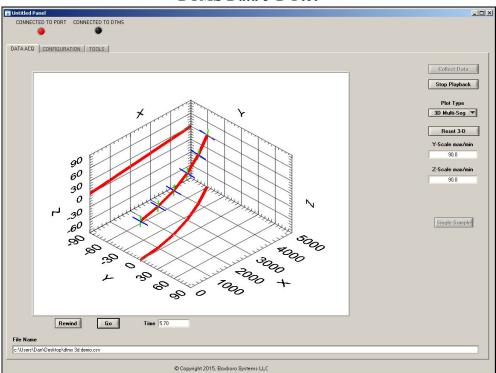


ACCESS BOXBORO DTMS MODEL 47 S/N 103 S/N 103

**Multi-Segment Schematic** 



**DTMS Data 3-D Plot** 



For more information, go to <u>www.boxborosystems.com</u> or contact Dan Handman, 978-257-2219, <u>dan@boxborosystems.com</u>